

TrueGrid[®] Output Manual For ANSYS[®]

A Guide and a Reference

by

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Version 2.3.0

XYZ Scientific Applications, Inc.

May 8, 2009

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I. ANSYS® Output Guide

This manual teaches the use of **TrueGrid**® when applied to a model to serve as input to the ANSYS® finite element simulation code. The generation of the geometric model is covered extensively in the **TrueGrid**® User's Manual and is not repeated here. There are many other features needed for a complete input to ANSYS® which are covered in this manual. Below is a list of some of the non-geometry commands that you may require to build a complete model.

title to set the problem title
plane to define symmetry planes
rotation to assign rigid body rotation
velocity to assign rigid body velocity
mate to select a material number for a part
jd to define numbered shared nodal degrees of freedom
spd to define the properties of numbered springs and dampers
bsd to define beam cross section properties
quadratic to generate 2nd order brick and shell elements
linear to return to generating 1st order brick and shell elements
mt to select a material for a region of a part
b to constrain nodal degrees of freedom
n to orient shell elements
or to orient local material coordinate systems within the element
fc to specify nodal forces (use 0 for the load curve)
mom to assign nodal moments (use 0 for the load curve)
fd to specify fixed nodal displacements (use 0 for the load curve)
fa to specify fixed nodal rotations
ndl for distributed nodal loads
pr to generate surface pressures (use 0 for the load curve)
pramp to specify pressure amplitude
dom to specify the domain of pramp
th to set shell thickness in a region different from the default
te to define constant nodal temperatures for temperature dependent materials
vhg to generate heat generating elements (use 0 for the load curve)
cvt to generate convection thermal loads
hfl to generate nodal flux, flow, amps, and heat conditions
mp to set the scalar magnetic potential
v to set the electrostatic potential
pm to assign mass to a existing node
npm to create a node and assign a mass to it
nset to assign nodes to named nodal sets
mpc to assign shared nodal (multiple point) constraints for a nodal set

jt to specify nodes shared degrees of freedom
spdp to specify a face to form a surface of springs/dampers
spring to create a numbered spring

The following commands are specific to the interface to ANSYS® and are discussed in detail below:

ansys to select the ANSYS® output format
ansyopts to define analysis options
ansymats to define element and material properties

You may want to view some of the properties graphically using the **condition (co)** command in the merge phase. The **tmm** command can be used to calculate the mass of each part. Be sure to merge the nodes using one of the merging commands such as **stp** and, finally, use the **ansys** command to select ANSYS® as the output option and the **write** command to actually create the input deck for ANSYS®.

The follow ANSYS® cards are generated using the commands listed above:

ACEL
ADAMS
ADAPT
ADDAM
ALPHAD
ANTYPE
ARCLEN
ARCTRM
AUTOTS
BETAD
BFE
BUCOPT
CGLOC
CGOMGA
CM
CMATRIX
CNVTOL
CP
CQC
CRPLIM
CSYS
/COM
CUTCONTROL
CYCOPT

D
DCGOMG
DDSOPT
DELTIM
DMPRAT
DOMEGA
DSUM
DSYM
EMATWRITE
EMORE
EN
EQSLV
ERESX
ESEL
ET
EXPASS
F
FINISH
FREQ
FSRS
GAUGE
GRP
HARFRQ
HFEIGOPT
HFPCSWP
HFSCAT
HFSWEEP
HREXP
HROPT
HROUT
KEYOPT
LMATRIX
LNSRCH
LOCAL
LUMPM
LVSCALE
MAT
MDAMP
MODOPT
MONITOR
MP
MPDATA
MPTEMP

MSAVE
MXPAND
N
NCNV
NEQIT
NLGEOM
NRLSUM
NROPT
NSEL
OMEGA
OPNCONTROL
PRECISION
PRED
PSDSPL
PSDUNIT
PSDWAV
PSOLVE
PSTRES
R
RATE
REAL
RIGID
RMODIF
RMORE
ROCK
SECNUM
SECOFFSET
SECREAD
SECTYPE
SED
SEEXP
SEOPT
SF
SFE
SOLCONTROL
/SOLU
SPOPT
SRSS
SUBOPT
SV
SVTYP
TB
TBDATA

TBTEMP
TIME
TIMINT
TINTP
/TITLE
TOFFST
TRNOPT
TYPE
VDDAM

In case a keyword command is not generated by **TrueGrid**[®], use the **verbatim** command to create the exact line to be replicated in the output file. You may also wish to contact XYZ Scientific Applications at (925) 373-0628 or at info@truegrid.com to request that this feature be supported in later versions of **TrueGrid**[®]. The **verbatim** command saves you from inserting the keyword command into the ANSYS[®] input deck. This is particularly useful if you are rerunning the **TrueGrid**[®] session file as you evolve the model or make parametric changes to it.

There are a number of ANSYS[®] specific properties that can be specified. These properties are not explained here because they are explained in the **TrueGrid**[®] User's Manual. These properties include:

bsd to define beam cross section properties

sid to define the property of a contact surface

offset to start the number of nodes and elements from a number other than 1

II. ANSYS® Output Example

III. ANSYS® Output Reference

The syntax for commands are described below where literals are highlighted in bold. Symbols to be substituted are italicized. Square brackets indicate repetition of an argument list. Each command is described by an entry like the following:

command **summary description**

command *arguments* brief description of functionality
 with brief descriptions of what the *arguments* should be. Indentation is used to indicate a list of options.

Remarks

When present, the Remarks section describes the command in even greater detail. It may describe the context in which the command is normally used, and other commands used in association with this command. It may describe side effects. It may describe other, similar commands. In many cases, it includes a description of where to find the command in the menus.

ansymats **ANSYS® materials**

ansymats *mat_no stifn* [*material_option list_of_values*] ; **kon** *m* ;

where

<i>mat_no</i>	user-defined material number to be associated with the material and element (using mate or mat commands to set a material type within TrueGrid® will automatically invoke the element type of this command along with its material properties).
<i>stifn</i>	element type
stif4	for beam4 elastic
stif5	for solid5 3-d multi-field solid
stif16	for pipe16 elastic straight pipe
stif18	for pipe18 elastic curved pipe (elbow)
stif20	for pipe20 plastic straight pipe
stif24	for beam24 3-d thin-walled plastic beam
stif28	for shell28 shear/twist panel
stif30	for fluid30 3-d isoparametric acoustic fluid
stif41	for shell41 3-d membrane shell
stif43	for shell43 plastic quadrilateral shell
stif44	for beam44 3-d tapered unsymmetrical beam
stif45	for solid45 3-d isoparametric solid

stif46	for solid46 8-node layered solid
stif57	for shell57 isoparametric quadrilateral thermal shell
stif58	for hyper58 u-p hyperelastic
stif59	for pipe59 immersed pipe or cable
stif60	for pipe60 plastic curved pipe
stif62	for solid62 magnet-structural
stif63	for shell63 elastic quadrilateral shell
stif64	for solid64 3-d anisotropic solid
stif65	for solid65 reinforced concrete solid
stif69	for solid69 3-d thermal-electrical solid
stif70	for solid70 thermal isoparametric solid
stif80	for fluid80 3-d fluid element
stif86	for hyper86 3-d hyperelastic solid
stif89	for visco89 viscoelastic
stif90	for solid90 thermal
stif91	for shell91 8-node layered shell
stif93	for shell93 structural
stif95	for solid95 structural
stif96	for solid96 magnetic scalar
stif97	for solid97 magnetic
stif99	for shell99 linear layered structural
stif107	for visco107 large strain
stif117	for solid117 magnetic
stif120	for hf120 high-frequency
stif122	for solid122 electrostatic
stif128	for solid128 electrostatic p-element
stif142	for fluid142 fluid-thermal
stif143	for shell143 fluid-thermal
stif147	for solid147 structural p-element
stif150	for shell150 structural p-element
stif157	for shell157 thermal-electric
stif185	for solid185 structural brick
stif186	for solid186 quadratic structural brick
stif188	for beam188 finite strain beam
<i>material_option</i>	can include some, all or none of the following (depending on element type - see the ANSYS User's Manual or use a dialogue box).
ex	<i>elastic_young's_modulus</i> (x-direction)
ey	<i>elastic_young's_modulus</i> (y-direction)
ez	<i>elastic_young's_modulus</i> (z-direction)
alpx	<i>coefficient_of_thermal_expansion</i> (x-direction)
alpy	<i>coefficient_of_thermal_expansion</i> (y-direction)
alpz	<i>coefficient_of_thermal_expansion</i> (z-direction)

nuxy *poisson's_ratio*
nuyz *poisson's_ratio*
nuxz *poisson's_ratio*
prxy *major_poisson's_ratio* (in the xy-dir)
pryz *major_poisson's_ratio* (in the yz-dir)
prxz *major_poisson's_ratio* (in the xz-dir)
gxy *shear_modulus* (x-stress, y-strain)
gyz *shear_modulus* (y-stress, z-strain)
gxz *shear_modulus* (x-stress, z-strain)
dens *density*
mu *coefficient_of_friction*
damp *damping_coefficient*
kxx *thermal_conductivity* (x-direction)
kyy *thermal_conductivity* (y-direction)
kzz *thermal_conductivity* (z-direction)
ch *specific_heat*
emis *emissivity*
hf *convection_film_coefficient*
visc *viscosity*
rsvx *electrical_resistivity* (x-direction)
rsvy *electrical_resistivity* (y-direction)
rsvz *electrical_resistivity* (z-direction)
qrate *heat_generation_rate*
perx *electric_relative_x-permeabilities*
pery *electric_relative_y-permeabilities*
perz *electric_relative_z-permeabilities*
murx *magnetic_relative_x-permeabilities*
mury *magnetic_relative_y-permeabilities*
murz *magnetic_relative_z-permeabilities*
mgxx *magnetic_coercive_x-forces*
mgyy *magnetic_coercive_y-forces*
mgzz *magnetic_coercive_z-forces*
lsst *dielectric_loss_tangent*
reft *reference_temperature* (1 value with no semi-colon)
dth *default_shell_thickness* (1 value with no semi-colon)

list_of_values is a list of as many as 5 numbers associated with the *material_option*. Enter just one value for a non temperature-dependent property. The list must be terminated by a semi-colon. The *material_option* and *list_of_values* may be repeated as many times as desired.

kon m is the same as the "keyopt(n)=m" ANSYS options for the element types (see the ANSYS User's Manual); the permissible values of n and m depend on the element type. This option may be repeated as

many times as desired. Remember to terminate the command by a semi-colon. The possible options are hard-wired into the dialogue box for **ansymats** so that you will be unable to choose invalid options for a given element type.

Remarks

ansyopts ANSYS® analysis option

ansyopts *options* ;

where an *option* can be

antype *key* for analysis type

where *key* must be one of

0	for structural analysis
1	for buckling analysis
2	for modal analysis
3	for harmonic analysis
4	for transient analysis
7	for substructure analysis
8	for spectrum analysis
acel <i>x y z</i>	for linear acceleration
cgloc <i>x y z</i>	for origin location
cgomga <i>x y z</i>	for velocity
dcgomg <i>x y z</i>	for acceleration
omega <i>x y z</i>	for rotational velocity
domega <i>x y z</i>	for rotational acceleration
eqslv <i>label</i>	for equation solver

where *label* must be one of

front <i>tolerance</i>	for frontal direct equation
sparse <i>tolerance</i>	for sparse direct
jcg <i>tolerance</i>	for jacobi cg (in memory)
jcgo <i>tolerance</i>	for jacobi cg
iccg <i>tolerance</i>	for incomplete cholesky cg
pcg <i>multiplier tolerance</i>	for pre-conditioned cg (in memory)
pcgo <i>multiplier tolerance</i>	for pre-conditioned cg
amg <i>tolerance</i>	for algebraic multigrid
dds <i>tolerance</i>	for distributed domain
ddsb <i>tolerance</i>	for distributed domain beta
iter <i>tolerance</i>	for automatic selection

adams *options* ; for solves & writes flexible body info

where *options* can be

nmodes <i>n</i>	
kstress <i>key</i>	
kshell <i>key</i>	
adapt <i>options</i> ;	for adaptively meshes & solves
where <i>options</i> can be	
nsoln <i>n</i>	
stargt <i>v</i>	
ttargt <i>v</i>	
facmn <i>v</i>	
facmx <i>v</i>	
kypsm <i>key</i>	
kymac <i>key</i>	
cmatrix <i>options</i> ;	for electrostatic field & capacitance
where <i>options</i> can be	
symfac <i>f</i>	
condname <i>name</i>	
numcond <i>n</i>	
grndkey <i>key</i>	
capname <i>name</i>	
cutcontr <i>options</i> ;	for time step cutback
where <i>options</i> can be	
pls <i>strain</i>	
crp <i>ratio type</i>	
dsp <i>d</i>	
npoint <i>n</i>	
noiter <i>key</i>	
cycopt <i>options</i> ;	for cyclic nodal diameter solution
where <i>options</i> can be	
status	
default	
noddia (<i>start end [inc [key]] ;</i>);	
dof (<i>id [c1 c2 c3 c4 c5 c6] ;</i>);	
cycoler <i>t</i>	
cycmove <i>key</i>	
ddsopt <i>options</i> ;	for distributed domain server
where <i>options</i> can be	
config <i>mode</i>	
ndomains <i>n</i>	
ematwr <i>key</i>	for write element matrices
eresx <i>key</i>	for extrapolation of integration point
expass <i>key</i>	for expansion pass
fsrs <i>option</i>	for restart fluid-structure interaction

where the *option* can be

time *f*

ldstep *n*

gauge *option* for domain of edge-element formulation

where the *option* can be

tree

off

hfeigopt *cavity* for high frequency electromagnetic

hfscat *option* for high frequency scattering

where the *option* can be

off

scat

total

hfpcswp *f1 f2 fi n* for propagating constants

hfsweep *f1 f2 fi n p1 p2 p3 p4 a d n1 n2 vf vc* for harmonic response to hf wave
guide

lmatrix *f name1 name2 name 3* for differential inductance matrix

lumpm *n1 n2 key* for lumped mass matrix

monitor *n1 n2 key* for contents of monitor file

where *key* can be one of the following

ux

uy

uz

rotx

roty

rotz

temp

fx

fy

fz

mx

my

mz

heat

msave *key* for memory saving for pcg

opncontr *temp v n* for automatic time step

precisio *key* for machine precision

psolve *keys ;* for partial solution

where *keys* can be

cgsol

eigdamp

eigexp

eigfull	
eiglanb	
eigreduc	
eigunsym	
elform	
elprep	
redwrite	
triang	
rate <i>key</i>	for creep strain rate usage
seexp <i>type dof switch flag</i>	for substructure expansion pass
where <i>type</i> can be	
file <i>name</i>	
elenum <i>n</i>	
where <i>flag</i> can be	
on	
off	
seopt <i>file key_m key_p key_ss</i>	for substructure analysis
solcontr <i>key_opt key_ts option t</i>	for nonlinear solution defaults
where <i>option</i> can be	
nopl	
default	
incp	
toffset <i>t</i>	for temperature offset
arclen <i>options ;</i>	for activating the arc-length method.
where <i>options</i> can be	
on	to activate arc-length method
off	to deactivate arc-length method
maxarc <i>max</i>	for maximum multiplier of ref. arc-length radius
minarc <i>min</i>	for minimum multiplier of ref. arc-length radius
arctrm <i>options ;</i>	for arc-length solution control.
where <i>options</i> can be	
off	to not use arctrm to terminate analysis
l	to terminates analysis when first limit point is reached
u	to terminates analysis when displacement exceeds maximum
val <i>displacement</i>	for maximum desired displacement
node <i>node_number</i>	for displacement comparison node number
dof <i>label</i>	for degree of freedom
where <i>label</i> can be	
ux	
uy	
uz	
rotx	

roty
rotz

bucopt *method options* ;
 where *method* must be one of the following
 subsp for subspace iteration
 lanb for block lanczos

where *options* can be
 nmode #_modes for number of modes to extract
 shift node_number for shift point
 ldmulte multiplier for upper end of load multiplier range

cnvtol *label options* ; for nonlinear analyses convergence.
 where *label* must be one of the following
 stat
 u
 rot
 f
 m
 temp
 heat
 pres
 v
 flow
 vf
 volt
 emf
 curr
 amps
 curt
 mag
 a
 curm
 flux
 csg
 vltg
 off
 l
 u

where *options* can be
 value *value* for typical value for label
 toler *tolerance*
 norm *type*
 where *type* is

	2	for l2 norm
	1	for l1 norm
	0	for infinite norm
minref	<i>minimum</i>	for minimum for allowed reference value
crplim	<i>type cvalue ;</i>	for creep criterion.
	where <i>type</i> must be one of the following	
	on	for implicit creep analysis
	off	for explicit creep analysis
	where <i>cvalue</i> must be	
	crcr	value for creep criteria value for creep limit ratio control
lnsrch	<i>key ;</i>	for newton-raphson line search.
	where <i>key</i> must be one of the following	
	off	to no use a line search
	on	to use a line search
	auto	for ansys to automatically switch line search on and off
ncnv	<i>options ;</i>	for analysis termination.
	where <i>options</i> can be	
	kstop	<i>key</i>
	where <i>key</i> is	
	0	to not terminate analysis if solution fails to converge
	1	to terminate the analysis and the program execution
	2	to terminate the analysis but not the program execution
	dlim	<i>limit</i> for nodal degrees of freedom limit
	itlim	<i>limit</i> for iteration count limit
	etlim	<i>limit</i> for elapsed time limit
	cplim	<i>limit</i> for cpu time limit
neqit	<i>niters ;</i>	for maximum number of equilibrium iterations
nlgeom	<i>key ;</i>	for including large deformation effects.
	where <i>key</i> must be one of the following	
	off	to ignore large-deflection effects
	on	to include large-deflection effects
nropt	<i>option switch ;</i>	for newton-raphson options.
	where <i>option</i> can be	
	auto	to let the program choose the option
	full	to use full newton-raphson
	modi	to use modified newton-raphson
	init	to use the previously computed matrix
	unsym	to use full newton-raphson with unsymmetric matrices
	where <i>switch</i> can be	
	off	to not use adaptive descent
	on	to use adaptive descent
pred	<i>options ;</i>	for predictor in a nonlinear analysis.

where *options* can be

offs	for subset predictor off
ons	for subset predictor on
offl	for load set predictor off
onl	for load set predictor on

pstres *key* ; for prestress effects.

where *key* must be one of the following

off	
on	

sstif *key* ; for stress stiffness effects.

where *key* must be one of the following

off	to not calculate (or include) prestress effect
on	to calculate (or include) prestress effect

alphad *v* for mass matrix multiplier for damping

betad *v* for stiffness matrix multiplier for damping

dmprat *v* for constant damping ratio

harfrq *options* ; for frequency range

where *options* can be

harfrqb <i>v</i>	
harfrqe <i>v</i>	

hrex *v* for phase angle

hropt *options* ; for harmonic analysis options

where *options* can be

method <i>type</i>	for solution method with options
where <i>type</i> can be	
full	for full method
reduc	for reduced method
msup	for mode superposition method
maxmode <i>n</i>	for largest mode number
minmode <i>n</i>	for smallest mode number

hrou *options* ; for harmonic analysis output options

where *options* can be

reimky <i>key</i>	for real/imaginary print:
where <i>key</i> can be	
on	for print complex displacements as real and imaginary
off	for print complex displacements as amplitude/phase angle
clust <i>key</i>	for cluster option:
where <i>key</i> can be	
on	for uniform spacing of frequency solutions
off	for cluster frequency solutions about natural frequency
mcont <i>key</i>	for mode contributions:
where <i>key</i> can be	

on	for no print of mode contributions at each frequency
off	for print mode contributions at each frequency
lvscale <i>v</i>	for scales load vector for mode superposition
mdamp <i>options</i> ;	for damping ratios as a function of mode
where <i>options</i> can be	
stloc <i>n</i>	for starting location in table for entering data
v1 <i>v1</i>	for first datum
v2 <i>v2</i>	for second datum
v3 <i>v3</i>	for third datum
v4 <i>v4</i>	for fourth datum
v5 <i>v5</i>	for fifth datum
v6 <i>v6</i>	for sixth datum
modopt <i>options</i> ;	for modal analysis options
where <i>options</i> can be	
method <i>label</i>	for mode extraction method for the modal analysis
where <i>label</i> can be	
lanb	for block lanczos
subsp	for subspace iteration
reduc	for householder (reduced)
unsym	for unsymmetric matrix
damp	for damped system
qrdamp	for damped system using qr algorithm
nmode <i>n</i>	for number of modes to extract
freqb <i>f</i>	for beginning, or lower end, of frequency range
freqe <i>f</i>	for ending, or upper end, of frequency range
prmode <i>n</i>	for number of reduced modes to print
nrmkey <i>key</i>	for mode shape normalization key:
where <i>key</i> can be	
off	for normalize the mode shapes to the mass matrix
on	for normalize the mode shapes to unity
cekey <i>n</i>	for constraint equation (ce) processing key
where <i>n</i> can be	
0	for lagrange multiplier method - accurate solution
1	for lagrange multiplier method - quick solution
2	for lagrange multiplier method - accurate solution
3	for direct elimination method
mxpand <i>options</i> ;	for the number of modes to expand/write
where <i>options</i> can be	
nmode <i>n</i>	for number of modes to expand and write
freqb <i>f</i>	for beginning, or lower end, of frequency range
freqe <i>f</i>	for ending, or upper end, of frequency range
elcalc <i>key</i>	for element calculation key:

where *key* can be

no	for do not calculate element results and reaction forces
yes	for calculate element results and reaction forces
signif <i>n</i>	for significance level
rigid <i>dof1 dof2 dof3 dof4 dof5 dof6</i>	for rigid body modes
subopt <i>options</i> ;	for subspace iteration eigenvalue extraction

where *options* can be

subsiz <i>s</i>	for subspace working size
npad <i>n</i>	for the number of extra vectors used in the iterations
nperbk <i>n</i>	for the number of modes per memory block
numssi <i>n</i>	for the maximum number of subspace iterations
nshift <i>n</i>	for the minimum number of subspace iterations completed
strmck <i>key</i>	for sturm sequence check key:

where *key* can be

all	to perform check at all shift points
part	to perform check only at all shift points
none	for do not perform sturm sequence check
jcgitr <i>n</i>	for the number of jacobi iterations per subspace iteration

timint *options* ;

where *options* can be

key <i>switch</i>	for transient effects:
--------------------------	------------------------

where *switch* can be

off	for no transient effects (static or steady-state)
on	for include transient (mass or inertia) effects

lab *lab*

where *lab* can be

all	to apply this key to all appropriate labels
struc	to apply this key to structural dofs
therm	to apply this key to thermal dofs
elect	to apply this key to electric dofs
mag	to apply this key to magnetic dofs
fluid	to apply this key to fluid dofs

tintp *options* ;

where *options* can be

gamma <i>v</i>	for amplitude decay factor for 2nd order transient
alpha <i>v</i>	for 2nd order transient integration parameter
delta <i>v</i>	for 2nd order transient integration parameter
theta <i>v</i>	for 1st order transient integration parameter
oslm <i>v</i>	for specifying the oscillation limit criterion
tol <i>t</i>	for tolerance applied to oslm. Defaults to 0.0
avsmooth <i>flag</i>	for smooth flag option:

where *flag* can be

0	to include smoothing of initial velocity/acceleration
1	to not include smoothing
trnopt options ;	for transient analysis
where <i>options</i> can be	
method label	for solution method with options
where <i>label</i> can be	
full	for full method
reduc	for reduced method
msup	for mode superposition method
maxmode n	for largest mode number
dmpkey key	for damping option (for method = reduc)
where <i>key</i> can be	
damp	to include the effects of damping if present
nodamp	to ignore the effects of damping
minmode n	for smallest mode number
addam options ;	for accel. spectrum computation constants
where <i>options</i> can be	
af coef	for direction-dependent accel. coeff.
aa coef	for coeff. for ddam accel. spectrum equations
ab coef	for coeff. for ddam accel. spectrum equations
ac coef	for coeff. for ddam accel. spectrum equations
ad coef	for coeff. for ddam accel. spectrum equations
amin min	for minimum accel. value
cqc option label ;	for quadratic mode combination method
where <i>option</i> can be	
signif threshold	for significance level for combining modes
where <i>label</i> can be	
disp	for displacement
velo	for velocity
acel	for acceleration
dsum options label ;	for double sum mode combination method.
where <i>options</i> can be	
signif threshold	for significance level for combining modes
td time	for time duration for earthquake or shock spectrum
where <i>label</i> can be	
disp	for displacement
velo	for velocity
acel	for acceleration
svfreq [load damp] ;	for sv vs freq definition (up to 4 pairs)
where <i>load</i> is the load curve for spectrum value .vs. frequency	
where <i>damp</i> is the damping ration for this curve (ansys sv damping)	
grp option label;	for grouping mode combination method.

where <i>option</i> can be	
signif <i>threshold</i>	for significance level for combining modes
where <i>label</i> can be	
disp	for displacement
velo	for velocity
acel	for acceleration
nrlsum <i>option label</i> ;	for nrl sum mode combination method.
where <i>option</i> can be	
signif <i>threshold</i>	for significance level for combining modes
where <i>label</i> can be	
disp	for displacement
velo	for velocity
acel	for acceleration
psdspl <i>options</i> ;	for partially correlated excitation in psd
where <i>options</i> can be	
tblno <i>n</i>	for input psd table number defined with psdval command
rmin <i>v</i>	for minimum distance between excitation points
rmax <i>v</i>	for maximum distance between excitation points
psdunit <i>options</i> ;	for type of psd/multi-pt response spectrum
where <i>options</i> can be	
tblno <i>n</i>	for input table number
type <i>label</i>	for identifying the type of spectrum:
where <i>label</i> can be	
disp	for displacement spectrum
velo	for velocity spectrum
acel	for acceleration spectrum
accg	for acceleration spectrum
forc	for force spectrum
pres	for pressure spectrum
gvalue <i>v</i>	for acceleration due to gravity for accg psd table
psdwav <i>tblno vx vy vz</i>	for wave propagation excitation in a psd analysis
<i>tblno</i>	the input psd table number defined with psdval command
<i>vx</i>	the global cartesian x-velocity of traveling wave
<i>vy</i>	the global cartesian y-velocity of traveling wave
<i>vz</i>	the global cartesian z-velocity of traveling wave
rock <i>cgx cgy cgz omx omy omz</i>	for a rocking response spectrum
<i>cgx cgy cgz</i>	for the x, y, and z location of center of rotation
<i>omx omy omz</i>	for the angular velocity components
sed <i>sedx sedy sedz</i>	for excitation direction for a single-pt. response spectrum
<i>sedx sedy sedz</i>	coordinates of a point that defines a line
spopt <i>options</i> ;	for spectrum type and other spectrum options
where <i>options</i> can be	

sptype <i>arg</i>	for the spectrum type:
where <i>arg</i> can be	
sprs	for single point excitation response spectrum
mprs	for multiple point excitation response spectrum
ddam	for dynamic design analysis method
psd	for power spectral density
nmode <i>n</i>	to use the first <i>n</i> modes from the modal analysis
elcalc <i>key</i>	for element calculation key (for sptype = psd only):
where the <i>key</i> can be	
no	for do not include stress responses in the calculations
yes	for include stress responses in the calculations
srss <i>options</i> ;	for square root of sum
where <i>options</i> can be	
signif <i>n</i>	for the significance level
label <i>label</i>	for identifying the combined mode solution output
where <i>label</i> can be	
disp	for displacement solution
velo	for velocity solution
acel	for acceleration solution
svtyp <i>options</i> ;	for the type of single-pt. response spectrum
where <i>options</i> can be	
ksv <i>n</i>	for response spectrum type:
where <i>n</i> can be	
0	for seismic velocity response spectrum loading
1	for force response spectrum loading
2	for seismic acceleration response spectrum loading
3	for seismic displacement response spectrum loading
4	for psd loading
fact <i>sf</i>	for scale factor applied to spectrum values
vddam <i>options</i> ;	for velocity spectrum constants
where <i>options</i> can be	
vf <i>c</i>	for direction-dependent velocity coefficient
vabc <i>a b c</i>	for coefficients for the ddam velocity spectrum

Remarks

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